

## Lecture Notes: Group Steiner Tree in General Graphs

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## 1 Group Steiner Tree

The input to the group Steiner tree (GST) problem is a graph  $G = (V, E)$  with costs  $d_e$  on edges  $e \in E$ , groups  $S_i \subseteq V$  (for  $i = 1, \dots, k$ ) and a root vertex  $r$ . The goal is to find minimal cost set of edges  $F$  that connects at least one  $v \in S_i$  to  $r$  for each  $i = 1, \dots, k$ . Recall from the last lecture:

**Theorem 1.1** *There is an  $O(H \log k)$ -approximation algorithm for GST when the graph  $G$  is a tree of depth  $H$ .*

When the given  $G = (V, E)$  is a general graph, we will show:

**Theorem 1.2** *There is an  $O(\log^2 n \log k)$ -approximation algorithm for GST on general graphs.*

## 2 Tree Embedding

The idea of tree embedding is to associate (a group of) tree  $T$  with edge-costs  $c$  to the given general graph  $G$  with edge-costs  $d$  such that the shortest path distances between any pair of vertices in  $G$  is bounded by the shortest path distances in  $T$ . We use  $\bar{d}(u, v)$  to denote the shortest path distance of  $u, v$  in  $G$ . Similarly,  $\bar{c}(u, v)$  is defined to be the shortest path distance in  $T$ .

The intuitive idea may be to find a deterministic  $T$  and edge cost  $c$  such that  $\forall u, v, \bar{d}(u, v) \leq \bar{c}(u, v) \leq \alpha \cdot \bar{d}(u, v)$ . But such a deterministic tree embedding is not very useful because  $\alpha$  has to be very large even on simple graphs. (The example is a cycle with  $n$  vertices. If remove one edge, one of the shortest path distances increases  $n - 1$  times. It can be proved that the *any* deterministic tree embedding incurs loss  $\alpha = \Omega(n)$ .)

We can approximate the given graph much better by using a randomized collection of trees.

**Definition 2.1** *Consider any graph  $G$  on vertices  $V$  and edge-costs  $d$ . Let  $\mathcal{D}$  be a distribution of trees (with edge-costs) on the same vertices  $V$ . Then  $\mathcal{D}$  is said to  $\alpha$ -probabilistically approximate distances in  $(G, d)$  if:*

1. for all  $u, v \in V$  and  $(T, c) \in \mathcal{D}$ ,  $\bar{c}(u, v) \geq \bar{d}(u, v)$ , and
2. for all  $u, v \in V$ ,  $\mathbb{E}_{(T, c) \leftarrow \mathcal{D}}[\bar{c}(u, v)] \leq \alpha \bar{d}(u, v)$ .

**Theorem 2.1** [1, 2] *Given an graph  $(G, d)$ , there is a randomized, polynomial-time algorithm that produces a distribution  $\mathcal{D}$  of trees that  $\alpha = O(\log n)$  probabilistically approximate distances in  $(G, d)$ . Moreover, the depth of each tree is  $O(\log n)$ .*

### 3 GST algorithm in general graphs

Using the tree embedding theorem, we have the following algorithm for GST in general graphs.

1. Randomly sample tree  $(T, c)$  from the distribution  $\mathcal{D}$  of tree embedding of  $(G, d)$ .
2. Run [GKR] algorithm (Theorem 1.1) on  $(T, c)$  to get  $F$ , which is a subset of edges on  $T$ .
3. Solution  $R$  is given by the union of shortest paths in  $G$  corresponding to each edge  $e \in F$ .

Recall Theorem 1.2, now we can prove it.

**Proof:** First note that  $R$  is always feasible. We want to show  $\mathbb{E}_{\mathcal{D}}[d(R)] \leq \alpha\rho OPT$  where  $\alpha$  is the factor in tree embedding and  $\rho$  is the approximation ratio on tree. Let  $R^*$  be the optimal solution in  $G$ . Let  $S^*$  be the union of all shortest paths in  $T$  corresponding to edges of  $R^*$ ; note that  $S^*$  is random as it depends on  $T$ . Then we have

$$\begin{aligned} \mathbb{E}_{\mathcal{D}}[c(S^*)] &\leq \mathbb{E}_{\mathcal{D}}\left[\sum_{(u,v) \in R^*} \bar{c}(u,v)\right] = \sum_{(u,v) \in R^*} \mathbb{E}_{\mathcal{D}}[\bar{c}(u,v)] \\ &\leq \alpha \sum_{(u,v) \in R^*} \bar{d}(u,v) \leq \alpha OPT, \end{aligned}$$

which comes from the second property of tree embedding. Since  $\rho$  is the approximation ratio on the tree instance, we have

$$\mathbb{E}_{\mathcal{D}}[c(F)] \leq \rho \mathbb{E}_{\mathcal{D}}[c(S^*)] \leq \rho\alpha OPT.$$

And by the first property of the tree embedding,

$$d(R) \leq \sum_{(u,v) \in F} \bar{d}(u,v) \leq \sum_{(u,v) \in F} \bar{c}(u,v) = c(F)$$

Take expectation of  $d(R)$  over  $\mathcal{D}$ , we have  $\mathbb{E}_{\mathcal{D}}[d(R)] \leq \mathbb{E}_{\mathcal{D}}[c(F)] \leq \alpha\rho OPT$ . ■

## References

- [1] FAKCHAROENPHOL, J., RAO, S., AND TALWAR, K. A tight bound on approximating arbitrary metrics by tree metrics. In *Proceedings of the thirty-fifth annual ACM symposium on Theory of computing* (2003), ACM, pp. 448–455.
- [2] GUPTA, A. Steiner points in tree metrics don't (really) help. In *Proceedings of the twelfth annual ACM-SIAM symposium on Discrete algorithms* (2001), Society for Industrial and Applied Mathematics, pp. 220–227.